

# 11 ELECTROMAGNETIC INDUCTION

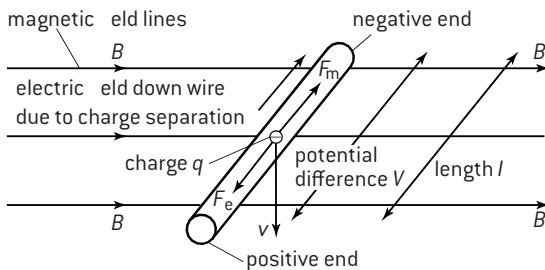
## HL Induced electromotive force (emf)

### INDUCED EMF

When a conductor moves through a magnetic field, an emf is induced. The emf induced depends on:

- The speed of the wire.
- The strength of the magnetic field.
- The length of the wire in the magnetic field.

We can calculate the magnitude of the induced emf by considering an electron at equilibrium in the middle of the wire. The induced electric force and the magnetic force are balanced.



Electrical force due to emf,  $F_e = E \times q = \left(\frac{V}{l}\right) \times q$

Magnetic force due to movement,  $F_m = Bqv$

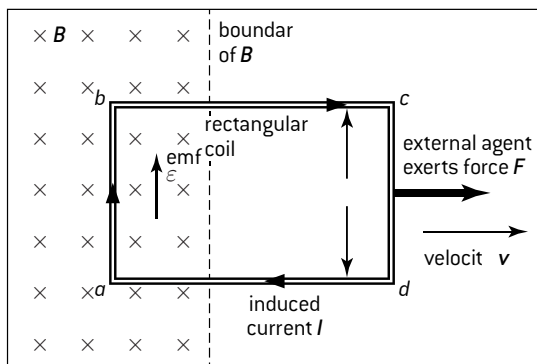
So  $Bqv = \left(\frac{V}{l}\right) q$

$$V = Blv$$

As no current is flowing, the emf  $\mathcal{E}$  = potential difference

$$\mathcal{E} = Blv$$

If the wire was part of a complete circuit (outside the magnetic field), the emf induced would cause a current to flow.



If this situation was repeated with a rectangular coil with  $N$  turns, each section  $ab$  would generate an emf equal to  $Bvl$ . The total emf generated will thus be

$$\mathcal{E} = BvIN$$

Note that in the situation above, a current only flows when one side of the coil ( $ab$ ) is moving through the magnetic field and the other side ( $cd$ ) is outside the field. If the whole coil was inside the magnetic field, each side would generate an emf. The two emfs would oppose one another and no current would flow.

### PRODUCTION OF INDUCED EMF BY RELATIVE MOTION

An emf is induced in a conductor whenever lines of magnetic flux are cut. But flux is more than just a way of picturing the situation; it has a mathematical definition.

If the magnetic field is perpendicular to the surface, the magnetic flux  $\phi$  passing through the area  $A$  is defined in terms of the magnetic field strength  $B$  as follows.

$$\phi = BA, \text{ so } B = \frac{\phi}{A}$$

In a uniform field,  $B = \frac{\phi}{A}$

An alternative name for 'magnetic field strength' is 'flux density'.

If the area is not perpendicular, but at an angle  $\theta$  to the field lines, the equation becomes

$$\phi = BA \cos \theta \text{ (units: T m}^2\text{)}$$

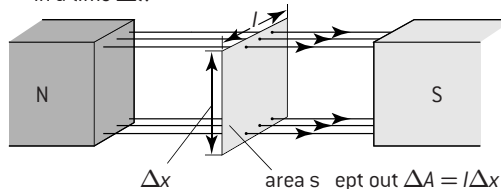
$\theta$  is the angle between  $\mathbf{B}$  and the normal to the surface.

Flux can also be measured in webers (Wb), defined as follows.

$$1 \text{ Wb} = 1 \text{ T m}^2$$

These relationships allow us to calculate the induced emf  $\mathcal{E}$  in a moving wire in terms of flux.

in a time  $\Delta t$ :



$$\mathcal{E} = Blv \text{ since } v = \frac{x}{t} \text{ then } \mathcal{E} = \frac{Blx}{t}$$

but  $lx = A$ , the area 'swept out' by the conductor in a time  $t$  so  $\mathcal{E} = \frac{BlA}{t}$

$$\text{but } B = \frac{\phi}{A} \text{ so } \mathcal{E} = \frac{\phi}{t}$$

In words, 'the emf induced is equal to the rate of cutting of flux'. If the conductor is kept stationary and the magnets are moved, the same effect is produced.

### EXAMPLE

An aeroplane flies at  $200 \text{ m s}^{-1}$ . Estimate the maximum pd that can be generated across its wings.

Vertical component

of Earth's magnetic field =  $10^{-5} \text{ T}$  (approximately)

Length across wings = 30 m (estimated)

$$\text{emf} = 10^{-5} \times 30 \times 200$$

$$= 6 \times 10^{-2} \text{ V}$$

$$= 0.06 \text{ V}$$

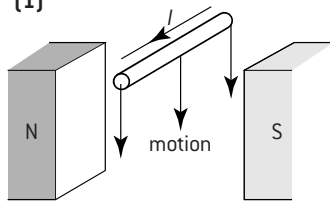
# HL Lenz's law and Faraday's law

## LENZ'S LAW

Lenz's law states that

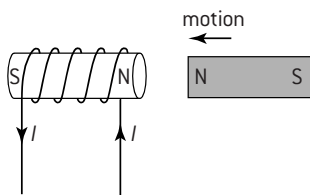
'The direction of the induced emf is such that if an induced current were able to flow, it would oppose the change which caused it.'

[1]



Current induced in this direction, the force would be upwards (left-hand rule)  
 $\therefore$  original motion would be opposed.

[2]



If current were induced this way, the induced field would repel the magnet — opposing motion.

Lenz's law can be explained in terms of the conservation of energy. The electrical energy generated within any system must result from work being done on the system. When a conductor is moved through a magnetic field and an induced current flows, an external force is needed to keep the conductor moving (the external force balances the opposing force that Lenz's law predicts). The external force does work and this provides the energy for the current to flow.

Put another way, if the direction of an induced current did not oppose the change that caused it, then it would be acting to support the change. If this was the case, then a force would be generated that further accelerated the moving object which would generate an even greater emf — electrical energy would be generated without work being done.

## TRANSFORMER-INDUCED EMF

An emf is also produced in a wire if the magnetic field changes with time.

If the amount of flux passing through one turn of a coil is  $\phi$ , then the total **flux linkage** with all  $N$  turns of the coil is given by

$$\text{Flux linkage} = N\phi$$

The universal rule that applies to all situations involving induced emf can now be stated as

'The magnitude of an induced emf is proportional to the rate of change of flux linkage.'

This is known as **Faraday's law**  $\varepsilon = N \frac{\Delta\phi}{\Delta t}$

Faraday's law and Lenz's law can be combined together in the following mathematical statement for the emf,  $\varepsilon$ , generated in a coil of  $N$  turns with a rate of change of flux through the coil of  $\frac{\Delta\phi}{\Delta t}$ :

$$\varepsilon = -N \frac{\Delta\phi}{\Delta t}$$

The dependence on the rate of change of flux and the number of turns is Faraday's law and the negative sign (opposing the change) is Lenz's law.

## APPLICATION OF FARADAY'S LAW TO MOVING AND ROTATING COILS

There are many situations involving magnetic fields with moving or rotating coils. To decide whether or not an emf is generated and, if it is, to calculate its value, the following procedure can be used:

- Choose the period of time,  $\Delta t$ , over which the motion of the coil is to be considered.
- At the beginning of the period, work out the flux passing through one turn of the coil,  $\phi_{\text{initial}}$ . Note that the shape of the coil is not relevant just the cross-sectional area.

$$\phi = BA \cos\theta.$$

- At the end of the period, work out the flux passing through one turn of the coil  $\phi_{\text{final}}$  using the equation above. Note that the sense of the magnetic field is important. If the magnitude of the field is the same but it is passing through the coil in the opposite direction, then

$$\phi_{\text{final}} = -\phi_{\text{initial}}$$

- Determine the change in flux,  $\Delta\phi$ :

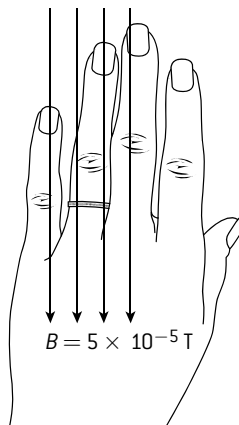
$$\Delta\phi = \phi_{\text{final}} - \phi_{\text{initial}}$$

- If there is no overall change of flux then, overall, no emf will be induced. If there is a change in flux then the emf induced in a coil of  $N$  turns will be:

$$\varepsilon = -N \frac{\Delta\phi}{\Delta t}$$

Example:

A physicist holds her hand so that the magnetic field of the Earth ( $50 \mu\text{T}$ ) passes through a ring on her hand.



In 0.1 s, she quickly turns her hand through  $90^\circ$  so that the magnetic field of the Earth no longer goes through the ring. Estimate the emf generated in the ring.

Answer:

Estimate of cross-sectional area of ring,  $A \approx 1 \text{ cm}^2 = 10^{-4} \text{ m}^2$

$$\phi_{\text{initial}} = 5 \times 10^{-5} \times 10^{-4} \cos(0) = 5 \times 10^{-9} \text{ Wb}$$

$$\phi_{\text{final}} = 0$$

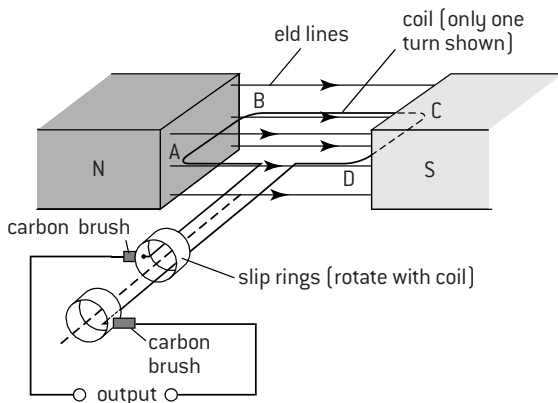
$$\therefore \Delta\phi = 5 \times 10^{-9} \text{ Wb}$$

$$\text{magnitude of } \varepsilon = N \frac{\Delta\phi}{\Delta t} = \frac{5 \times 10^{-9}}{10^{-1}} = 5 \times 10^{-8} \text{ V}$$

# HL Alternating current (1)

## COIL ROTATING IN A MAGNETIC FIELD – AC GENERATOR

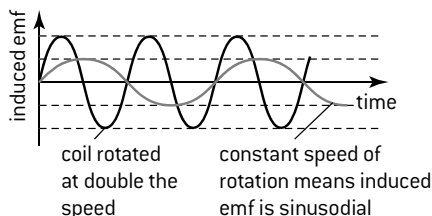
The structure of a typical ac generator is shown below.



ac generator

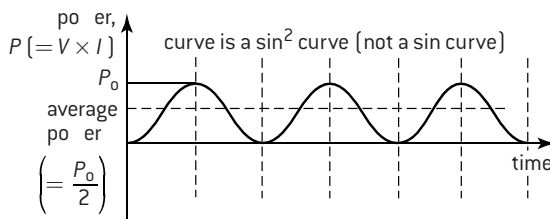
The coil of wire rotates in the magnetic field due to an external force. As it rotates the flux linkage of the coil changes with time and induces an emf (Faraday's law) causing a current to flow. The sides AB and CD of the coil experience a force opposing the motion (Lenz's law). The work done rotating the coil generates electrical energy.

A coil rotating at constant speed will produce a sinusoidal induced emf. Increasing the speed of rotation will reduce the time period of the oscillation and increase the amplitude of the induced emf (as the rate of change of flux linkage is increased).



## RMS VALUES

If the output of an ac generator is connected to a resistor an alternating current will flow. A sinusoidal potential difference means a sinusoidal current.



The graph shows that the average power dissipation is half the peak power dissipation of a sinusoidal current.

$$\text{Average power } \bar{P} = \frac{I_0^2 R}{2} = \left( \frac{I_0}{\sqrt{2}} \right)^2 R$$

Thus the effective current through the resistor is  $\sqrt{\text{mean value of } P}$  and it is called the **root mean square** current or **rms** current,  $I_{\text{rms}}$ .

$$I_{\text{rms}} = \frac{I_0}{\sqrt{2}} \quad (\text{or sinusoidal currents})$$

When ac values of voltage or current are quoted, it is the root mean square value that is being used. In Europe this value is 230 V, whereas in the USA it is 120 V.

$$V_{\text{rms}} = \frac{V_0}{\sqrt{2}}$$

$$\bar{P} = V_{\text{rms}} I_{\text{rms}} = \frac{1}{2} I_0 V_0$$

$$P_{\text{max}} = I_0 V_0$$

$$R = \frac{V}{I} = \frac{V_0}{I_0} = \frac{V_{\text{rms}}}{I_{\text{rms}}}$$

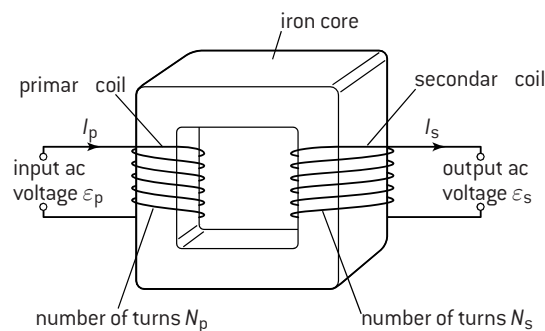
## TRANSFORMER OPERATION

An **alternating** potential difference is put into the transformer, and an **alternating** potential difference is given out. The value of the output potential difference can be changed (increased or decreased) by changing the **turns ratio**. A **step-up** transformer increases the voltage, whereas a **step-down** transformer decreases the voltage.

The following sequence of calculations provides the correct method for calculating all the relevant values.

- The output voltage is fixed by the input voltage and the turns ratio.
- The value of the load that you connect fixes the output current (using  $V = IR$ ).
- The value of the output power is fixed by the values above ( $P = VI$ ).
- The value of the input power is equal to the output power of an ideal transformer.
- The value of the input current can now be calculated (using  $P = VI$ ).

So how does the transformer manage to alter the voltages in this way?



$$\frac{\epsilon_p}{\epsilon_s} = \frac{N_p}{N_s} = \frac{I_s}{I_p}$$

Transformer structure

- The alternating pd across the primary creates an ac within the coil and hence an alternating magnetic field in the iron core.
- This alternating magnetic field links with the secondary and induces an emf. The value of the induced emf depends on the rate of change of flux linkage, which increases with increased number of turns on the secondary. The input and output voltages are related by the turns ratio.

# HL Alternating current (2)

## TRANSMISSION OF ELECTRICAL POWER

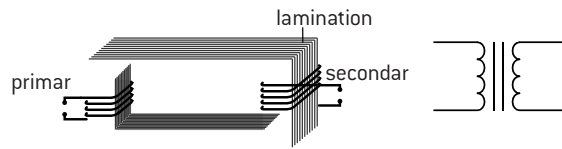
Transformers play a very important role in the safe and efficient transmission of electrical power over large distances.

- If large amounts of power are being distributed, then the currents used will be high. (Power =  $I^2 R$ )
- The wires cannot have zero resistance. This means they must dissipate some power
- Power dissipated is  $P = I^2 R$ . If the current is large then the (current)<sup>2</sup> will be very large.
- Over large distances, the power wasted would be very significant.
- The solution is to choose to transmit the power at a very high potential difference.
- Only a small current needs to flow.
- A very high potential difference is much more efficient, but very dangerous to the user.
- Use step-up transformers to increase the voltage for the transmission stage and then use step-down transformers for the protection of the end user.

## LOSSES IN THE TRANSMISSION OF POWER

In addition to power losses associated with the resistance of the power supply lines, which cause the power lines to warm up, there are also losses associated with non-ideal transformers:

- **Resistance of the windings (joule heating)** of a transformer result in the transformer warming up.
- **Eddy currents** are unwanted currents induced in the iron core. The currents are reduced by **laminating** the core into individually electrically insulated thin strips.
- **Hysteresis** losses cause the iron core to warm up as a result of the continued cycle of changes to its magnetism.
- **Flux** losses are caused by magnetic 'leakage'. A transformer is only 100% efficient if all of the magnetic flux that is produced by the primary links with the secondary.

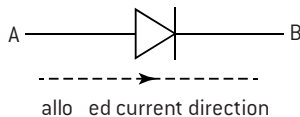


## DIODE BRIDGES

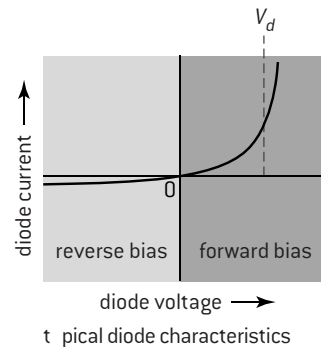
The efficient transmission of electrical power is best achieved using alternating current (ac) and transformers can ensure the appropriate  $V_{rms}$  is supplied. Many electrical devices are, however, designed to operate using direct current (dc). The conversion from ac into dc is called **rectification** which relies on diodes.

A **diode** is a two-terminal electrical device that has different electrical characteristics depending on which way around it is connected. An ideal diode allows current to flow in the forward direction (negligible resistance with forward bias) but does not allow current to flow in the reverse direction (infinite resistance with reverse bias).

Symbol:



Current is allowed to flow from A to B (A is positive and B is negative) but is prevented from following from B to A (A is negative and B is positive).

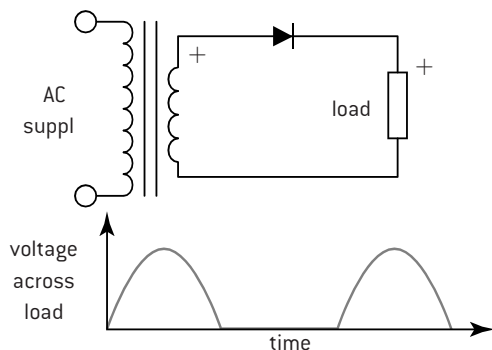


# HL Rectification and smoothing circuits

## RECTIFICATION

### 1. Half-wave rectification

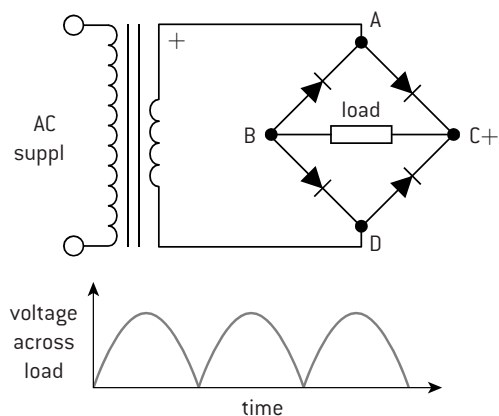
A single diode will convert ac into a pulsating dc:



In half-wave rectification, electrical energy that is available in the negative cycle of the ac is not utilized.

### 2. Full-wave rectification

A diode bridge (using four diodes) can utilize all the electrical energy that is available during a complete cycle as shown below.



In the positive half of the cycle, current flows through the diode bridge from A → C → B → D.

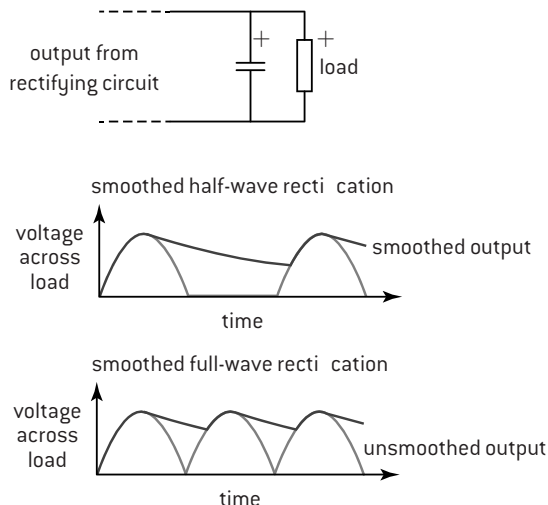
In the negative half of the cycle, current flows through the diode bridge from D → C → B → A.

Note that:

- Current always flows through the load resistor in the same direction. (C → B)
- Diodes on parallel sides point in the same directions.
- The ac signal is fed to the points where opposite ends of two diodes join.
- The positive output is taken from the junction of the negative side of two diodes.
- The negative output is taken from the junction of the positive side of two diodes.
- During each half-cycle one set of parallel-side diodes conducts.

## SMOOTHING CIRCUITS

Diode-bridge circuits provide a current that flows in one direction (dc) but still pulsates. In order to achieve a steady pd, a **smoothing** device is required. One possibility is a **capacitor** (see page 117 for more details).



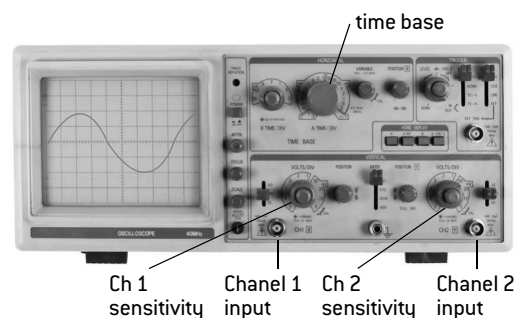
Note that:

- The output is still fluctuating slightly; this is known as the output **ripple**.
- The capacitor is acting as a short-term store of electrical energy.
- The capacitor is constantly charging and discharging.
- In order to ensure a slow discharge, the value of the capacitor  $C$  needs to be chosen to ensure that the time constant (see page 118) is sufficiently large.

## INVESTIGATING A DIODE-BRIDGE RECTIFICATION CIRCUIT EXPERIMENTALLY

The display of the varying pd across the load is best achieved using a cathode ray oscilloscope (CRO).

The **y-input control**, allows the sensitivity of the CRO to appropriately display a changing pd on the y-axis. The **time-base controls** allows an appropriate calibration of the x-axis to match the time period of the oscillations.



time base set at  $2.5 \text{ ms cm}^{-1}$

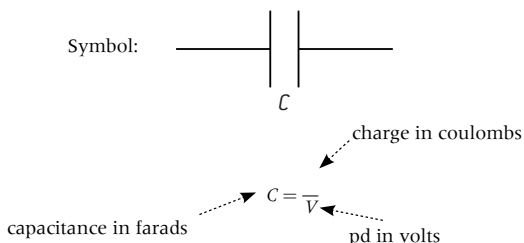
1 oscillation = 8 cm on screen = 20 ms

$$\therefore \text{frequency} = \frac{1}{0.02} = 50 \text{ Hz}$$

# HL Capacitance

## CAPACITANCE

Capacitors are devices that can store charge. The charge stored is proportional to the pd across the capacitor  $V$  and the constant of proportionality is called the capacitance  $C$ .



The farad (F) is a very large unit and practical capacitances are measured in  $\mu\text{F}$ , nF or pF.

$$1 \text{ F} = 1 \text{ C V}^{-1}$$

A measurement of the pd across a capacitance allows the charge stored to be calculated.

The capacitance of a parallel plate capacitor depends on three different factors:

- The area of each plate,  $A$ . Each plate is assumed to have the same area  $A$  and the plates overlap one another completely.
- The separation of the plates,  $d$
- The material between the plates which is called the **dielectric material**. Different materials will have different values of a constant called its **permittivity**,  $\epsilon$ . The permittivity of air is effectively the same as the permittivity of a vacuum (free space),  $\epsilon_0 = 8.85 \times 10^{-12} \text{ C}^2 \text{ N}^{-1} \text{ m}^{-2}$ . The permittivity of all substances is greater than  $\epsilon_0$ .

The relationship is:

$$C = \frac{\epsilon A}{d}$$

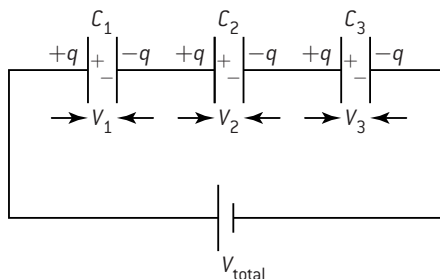
when a dielectric material is introduced, charge separation across the dielectric is induced. This increases the capacitance.

## CAPACITORS IN SERIES AND PARALLEL

The effective total capacitance,  $C_{\text{total}}$ , of the combination of capacitors ( $C_1$ ,  $C_2$ ,  $C_3$ , etc.) in a circuit depends on whether the capacitors are joined together in series or in parallel. The capacitor equation can be used on individual capacitors or on the combination.

$$C_{\text{total}} = \frac{q_{\text{total}}}{V_{\text{total}}} \text{ and } C_1 = \frac{q_1}{V_1}, C_2 = \frac{q_2}{V_2}, \text{ etc.}$$

### 1. In series



The charge stored in each capacitor is the same, and the pds across the individual capacitors add together to give the total pd

$$q_{\text{total}} = q_1 = q_2 = q_3 = q$$

$$V_{\text{total}} = V_1 + V_2 + V_3$$

$$\therefore \frac{q_{\text{total}}}{C_{\text{total}}} = \frac{q}{C_1} + \frac{q}{C_2} + \frac{q}{C_3}$$

$$\therefore \frac{1}{C_{\text{series}}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3}$$

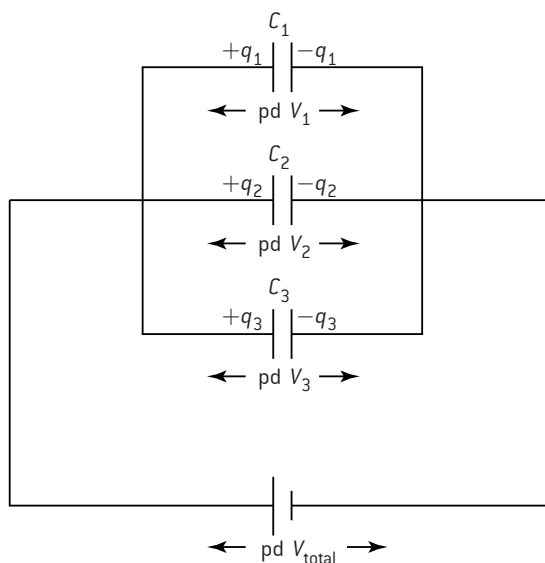
$$\frac{1}{C_{\text{series}}} = \frac{1}{C_1} + \frac{1}{C_2} + \dots$$

e.g. if three capacitors 5 F, 10 F and 20 F are added in series, the combined capacitance is:

$$\frac{1}{C_{\text{series}}} = \frac{1}{5} + \frac{1}{10} + \frac{1}{20} = \frac{7}{20} \text{ F}^{-1}$$

$$\therefore C_{\text{series}} = \frac{20}{7} = 2.86 \text{ F}$$

### 2. In parallel



The pd across each capacitor is the same,  $V$  and the charges stored in each of the individual capacitors add together to give the total charge stored.

$$V_{\text{total}} = V_1 = V_2 = V_3 = V$$

$$q_{\text{total}} = q_1 + q_2 + q_3$$

$$\therefore C_{\text{total}} V_{\text{total}} = C_1 V_1 + C_2 V_2 + C_3 V_3$$

$$\therefore C_{\text{parallel}} V = C_1 V + C_2 V + C_3 V$$

$$\therefore C_{\text{parallel}} = C_1 + C_2 + \dots$$

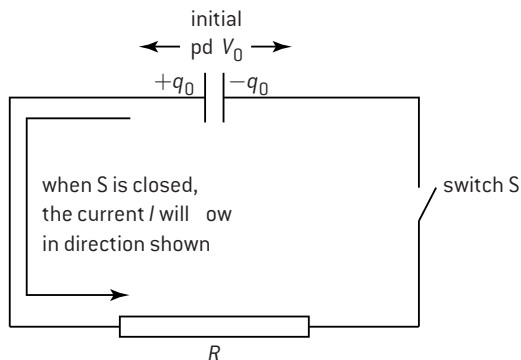
e.g. if three capacitors 5 F, 10 F and 20 F are added in parallel, the combined capacitance is:

$$C_{\text{parallel}} = 5 + 10 + 20 = 35 \text{ F}$$

# HL Capacitor discharge

## CAPACITOR (RC) DISCHARGE CIRCUITS

If the two ends of a charged capacitor are joined together with a resistor, a current will flow until the capacitor is discharged.



During the discharge process:

- the value of the discharge current,  $I$ , drops from an initial maximum  $I_0$  down to zero
- the value of the stored charge,  $q$ , drops from an initial maximum  $q_0$  down to zero
- the value of the pd across the capacitor (which is also the pd across the resistor),  $V$ , drops from an initial maximum  $V_0$  down to zero.

Applying Kirchoff's law around the loop gives

$$0 = IR + \frac{q}{C}$$

Since  $I$  is the rate of flow of charge,  $\frac{dq}{dt}$ ,

$$0 = R \frac{dq}{dt} + \frac{q}{C}$$

$$\frac{dq}{dt} = -\frac{q}{RC}$$

This has the rate of flow of charge proportional to the charge stored. The solution is an exponential decrease of charge stored given by:

$$q = q_0 e^{-\frac{t}{RC}}$$

time (s)
capacitance (F)
resistance ( $\Omega$ )

charge remaining
original charge

The product of  $RC$  is called the **time constant** of the circuit and is given the symbol  $\tau$  (the Greek letter tau).

$$\tau = RC$$

The SI unit of  $\tau$  will be seconds (NB: care needed with SI multipliers).

$$q = q_0 e^{-\frac{t}{\tau}}$$

Since the current  $I$  and the pd  $V$  are both proportional to the charge, the following equations also apply:

$$I = I_0 e^{-\frac{t}{\tau}}$$

$$V = V_0 e^{-\frac{t}{\tau}}$$

Where

$$I_0 = \frac{q_0}{RC} = \frac{V_0}{R}$$

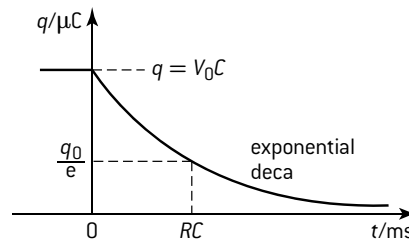
Example

A  $10 \mu\text{F}$  capacitor is discharged through a  $20 \text{ k}\Omega$  resistor. Calculate (a) the time constant  $\tau$  of the circuit and (b) the fraction of charge remaining after one time constant

a)  $\tau = RC = 10 \mu\text{F} \times 20 \text{ k}\Omega = 200 \text{ ms}$

b) After one time constant,

$$q = q_0 e^{-1} = 0.37q_0$$



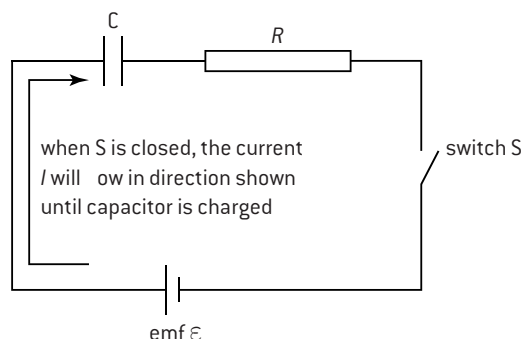
time	charge
0	100%
1RC	37%
2RC	14%
3RC	5%
4RC	2%
5RC	<1%

After 5 time constants, the capacitor is effectively discharged

# HL Capacitor charge

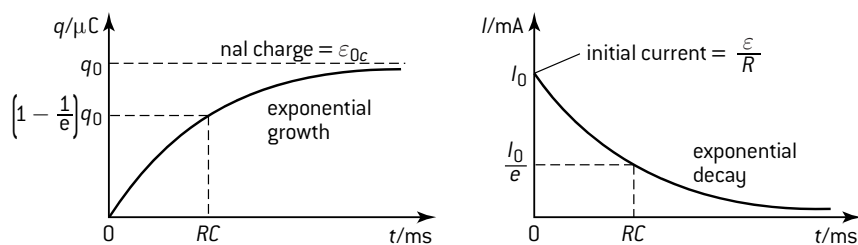
## CAPACITOR CHARGING CIRCUITS

If the two ends of an uncharged capacitor are joined together with a resistor, a current will flow until the capacitor is charged.



During the charging process,

- the value of the charging current,  $I$ , drops from an initial maximum  $I_0$  down to zero
- the value of the stored charge,  $q$ , increases from zero up to a final maximum value,  $q_0$
- the value of the pd across the capacitor,  $V$ , increases from zero up to a final maximum value,  $\varepsilon$
- the value of the pd across the resistor drops from an initial maximum  $\varepsilon$  down to zero.

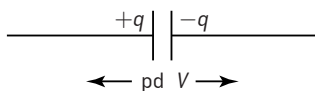


The equation for the increase of charge on the capacitor (which does not need to be memorized) is:

$$q = q_0 \left(1 - e^{-t/RC}\right)$$

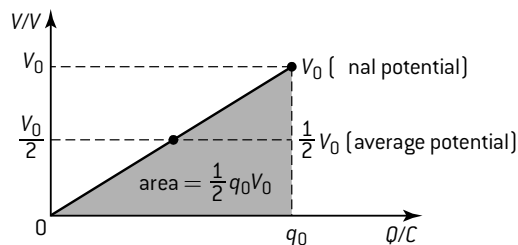
## ENERGY STORED IN A CHARGED CAPACITOR

A charged capacitor can provide a temporary store of electrical energy when there is a potential difference  $V$  across the capacitor. The charge,  $q$ , that is stored is distributed with  $+q$  on one plate and  $-q$  on the other plate as shown below. There is an electric field between the plates.



In the charging process, as more charge is added to the capacitor, the pd across it also increases proportionally.

The graph (right) shows how the pd across the capacitor varies with charge stored in the capacitor during the charging process. The total energy stored,  $E$ , is represented by the area under the graph.



$$E = \frac{1}{2} qV = \frac{1}{2} \frac{q^2}{C} = \frac{1}{2} CV^2$$

Note that both charging and discharging are exponential processes. If a circuit is arranged in which a capacitor spends equal time charging and discharging through the same value resistor, then in one complete cycle, more charge will be added to the capacitor during the charging time than it loses during the discharging time. The result over several cycles will be for the capacitor to charge up to the same pd as the power supply.



# HL IB Quest ons – electromagnet c nduct on

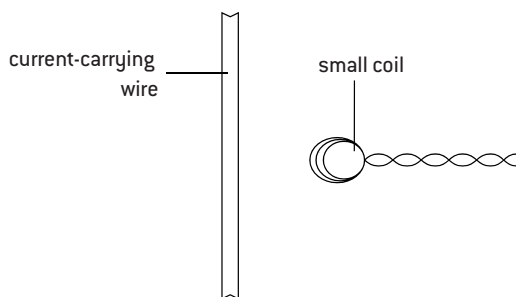
1. The **primary** of an ideal transformer has 1000 turns and the **secondary** 100 turns. The current in the primary is 2 A and the input power is 12 W.

Which **one** of the following about the **secondary current** and the **secondary power output** is true?

	secondary current	secondary power output
A.	20 A	1.2 W
B.	0.2 A	12 W
C.	0.2 A	120 W
D.	20 A	12 W

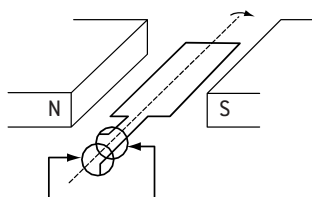
2. This question is about electromagnetic induction.

A small coil is placed with its plane parallel to a long straight current-carrying wire, as shown below.



- a) (i) State Faraday's law of electromagnetic induction. [2]  
 (ii) Use the law to explain why, when the current in the wire changes, an emf is induced in the coil. [1]

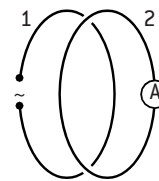
3. The diagram shows a simple generator with the coil rotating between magnetic poles. Electrical contact is maintained through two brushes, each touching a slip ring.



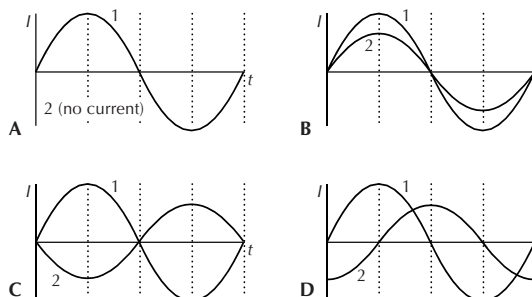
At the instant when the rotating coil is oriented as shown, the voltage across the brushes

- A. is zero.  
 B. has its maximum value.  
 C. has the same constant value as in all other orientations.  
 D. reverses direction.
4. The rms current rating of an electric heater is 4A. What direct current would produce the same power dissipation in the electric heater? [2]
- A.  $\frac{4}{\sqrt{2}}$  A                      B. 4A  
 C.  $4\sqrt{2}$  A                      D. 8A

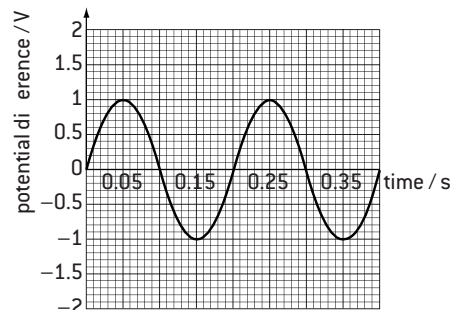
5. Two loops of wire are next to each other as shown here. There is a source of alternating emf connected to loop 1 and an ammeter in loop 2.



The variation with time of the current in loop 1 is shown as line 1 in each of the graphs below. In which graph does line 2 best represent the current in loop 2?



6. A loop of wire of negligible resistance is rotated in a magnetic field. A  $4\ \Omega$  resistor is connected across its ends. A cathode ray oscilloscope measures the varying induced potential difference across the resistor as shown below.



- a) If the coil is rotated at twice the speed, show on the axes above how potential difference would vary with time. [2]  
 b) What is the rms value of the induced potential difference,  $V_{rms}$ , at the **original** speed of rotation? [1]  
 c) Draw a graph showing how the power dissipated in the resistor varies with time, at the **original** speed of rotation. [3]
7. a) A  $3\ \mu\text{F}$  capacitor is charged to 240 V. Calculate the charge stored. [1]  
 b) Estimate the amount of time it would take for the charge you have calculated in (a) to flow through a 60 W light bulb connected to the 240 V mains electricity. [2]  
 c) The charged capacitor in (a) is discharged through a 60 W 240 V light bulb.  
 (i) Explain why the current during its discharge will not be constant. [2]  
 (ii) Estimate the time taken for the capacitor to discharge through the light bulb. [2]  
 (iii) Will the bulb light during discharge? Explain your answer. [2]